Programming with Universes, Generically

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An introduction to Agda

Agda

- Functional programming language
- Static types
- Dependent types
- Pure (explicit effects)
- Total (mostly)



Agda

- Functional programming language
- Static types
- Dependent types
- Pure (explicit effects)
- Total (mostly)
- Actively developed at Chalmers University
- Ulf Norell and many others
- Written in Haskell



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```
data List (A : Set) : Set where

[] : List A

_::_: : A \rightarrow List A \rightarrow List A

map : {A B : Set} \rightarrow (A \rightarrow B) \rightarrow List A \rightarrow List B

map f[] = []

map f(x :: xs) = f x :: map f xs
```



Dependent types

Types can depend on terms:

 $\begin{array}{ll} \mbox{data Vec } (A : Set) : \mathbb{N} \rightarrow Set \mbox{ where} \\ [] & : Vec \mbox{ A zero} \\ _ ::_ : \{n : \mathbb{N}\} \rightarrow A \rightarrow Vec \mbox{ A } n \rightarrow Vec \mbox{ A } (suc \ n) \\ _ ++_ : \{A : Set\} \{m \ n : \mathbb{N}\} \rightarrow \\ & Vec \ A \ m \rightarrow Vec \ A \ n \rightarrow Vec \ A (m + n) \\ [] & + ys = ys \\ (x :: xs) + ys = x :: (xs + ys) \end{array}$



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- Computation during type-checking
- When are two types equal?



Are these equal? Vec \mathbb{N} (2 + 2) Vec \mathbb{N} 4



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And these?
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Simple rule: types are reduced according to their definitions as far as possible and then checked for (alpha-)equality.



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Simple rule: types are reduced according to their definitions as far as possible and then checked for (alpha-)equality.

- 2+2 reduces to 4, so the first two are equal.
- n + 1 is stuck, because _+_ is defined by induction on the first argument. The second two are not equal.



Programs and Proofs

Function in Agda are supposed to be total:

- defined on all inputs,
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So, despite computation on the type level, type checking is decidable.



Enforcing totality

Relatively simple (but conservative) checks:

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- Datatypes must be strictly positive.

Consequence: Agda has uninhabited types!

data \perp : Set where

No constructors, thus no way to construct values of type \perp .

Whereas in Haskell:

loop :: forall a. a loop x = x



Curry-Howard isomorphism

Agda becomes interesting as a logic.

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proof	program



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negation	function to the uninhabited type



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negation	function to the uninhabited type
universal quantification	dependent function
existential quantification	dependent pair



A type representing equality

data
$$_\equiv_{-} \{A : Set\} : A \rightarrow A \rightarrow Set$$
 where
refl : $\{x : A\} \rightarrow x \equiv x$

The value refl is a **witness** that two terms of type A are actually equal.



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Where Agda's built-in (definitional) equality isn't enough, we can explicitly prove (and use) equality using $\square \equiv \square$.



Programming is proving

Equality is a congruence: cong : $\{A B : Set\} \{x y : A\} \rightarrow$ (f : A \rightarrow B) $\rightarrow x \equiv y \rightarrow f x \equiv f y$ cong f refl = refl



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```

Zero is a right-unit of addition:

```
\begin{array}{ll} example \ : \ (n \ : \ \mathbb{N}) \to (n + zero) \equiv n \\ example \ zero & = \ refl \\ example \ (suc \ n) \ = \ cong \ suc \ (example \ n) \end{array}
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Proofs are easier to do interactively.



Dependently typed programming

- Programming with data that maintains complex invariants, verified by the type checker.
- Stating and proving properties about programs within the program, using the same language.
- Using precise types to guide the programming process.



Datatype-genericity

Types make things different.

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They sometimes seem to stand in the way of **code reuse**.

A lot of this tension is already addressed by **polymorphism**, which now corresponds to **universal quantification**.

But what if we want different (but related) behaviour for different types?



Datatype-generic programs allow you to **inspect the structure of datatypes** while defining a function.



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Classic examples:

- structural equality, structural ordering
- serialization, deserialization
- parsing, pretty-printing
- mapping, traversing, transforming, querying



Historical context

- Active research topic since about 15 years.
- A lot of promising approaches, many based on Haskell.
- Related to OO design patterns such as Visitor and Iterator, but also to techniques such as model-driven design.
- Related to meta-programming, but with the goal to be type-safe.
- Historically required significant language extensions or a preprocessor.
- Advances in FP type systems have made it possible to develop datatype-generic programs (nearly) directly in Haskell.
- Dependent types are even more powerful than current Haskell, so DGP in Agda should be easy ...



Universes

Universe

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We cannot inspect types directly.

But we can inspect codes!

A (datatype-)generic function is a function defined by induction on the codes:

$$\mathsf{gf} \ : \ (\mathsf{C} \ : \ \mathsf{Code}) \to \ \ldots \ \llbracket \ \mathsf{C} \ \rrbracket \ \ldots$$



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```
data Vec (A : Set) : \mathbb{N} \rightarrow Set where
[] : Vec A zero
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Here, \mathbb{N} are the codes, and Vec is an A -indexed family of interpretation functions.



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Thus $_++_$ is a generic function on this universe.



A different way to define the vector universe

Again, we use \mathbb{N} as type of codes.

 $\begin{array}{lll} \mbox{Vec} : (A : Set) \rightarrow \mathbb{N} \rightarrow Set \\ \mbox{Vec} \mbox{ A zero } &= \top \\ \mbox{Vec} \mbox{ A (suc n) } &= \mbox{ A \times Vec} \mbox{ A n} \end{array}$



Another interpetation for natural numbers

With Fin , we define the family of finite types:

 $\begin{array}{ll} \mathsf{Fin} \, : \, \mathbb{N} \to \mathsf{Set} \\ \mathsf{Fin} \, \mathsf{zero} &= \, \bot \\ \mathsf{Fin} \, (\mathsf{suc} \; \mathsf{n}) \, = \, \top \uplus \mathsf{Fin} \; \mathsf{n} \end{array}$



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```

Safe lookup:



Another definition for finite types

Finite types are closed under union and cartesian product:

```
data Code : Set where
```

```
\begin{array}{rll} c0 & : \mbox{ Code} \\ c1 & : \mbox{ Code} \\ \_\oplus\_ & : \mbox{ Code} \rightarrow \mbox{ Code} \rightarrow \mbox{ Code} \end{array}
```

```
\_\otimes\_: \mathsf{Code} \to \mathsf{Code} \to \mathsf{Code}
```

```
 \begin{array}{ll} \llbracket \_ \rrbracket : \mathsf{Code} \to \mathsf{Set} \\ \llbracket \mathsf{c0} & \rrbracket &= \bot \\ \llbracket \mathsf{c1} & \rrbracket &= \top \\ \llbracket \mathsf{C} \oplus \mathsf{D} \rrbracket &= \llbracket \mathsf{C} \rrbracket \uplus \llbracket \mathsf{D} \rrbracket \\ \llbracket \mathsf{C} \otimes \mathsf{D} \rrbracket &= \llbracket \mathsf{C} \rrbracket \times \llbracket \mathsf{D} \rrbracket \end{array}
```



Generic equality on finite types

$$\begin{array}{l} _==_: (C : Code) \rightarrow [\![C]\!] \rightarrow [\![C]\!] \rightarrow Bool \\ _=_c0 \qquad () () \\ _==_c1 \qquad tt \ tt \ = \ true \\ _=_(C \oplus D) \ (inj_1 \ x_1) \ (inj_1 \ x_2) \ = \ _==_C \ x_1 \ x_2 \\ _=_(C \oplus D) \ (inj_2 \ y_1) \ (inj_2 \ y_2) \ = \ _==_D \ y_1 \ y_2 \\ _==_(C \oplus D) \ _ \ _ \ = \ false \\ _=_(C \otimes D) \ (x_1 \ , y_1) \ (x_2 \ , y_2) \ = \ _==_C \ x_1 \ x_2 \land _==_D \ y_1 \ y_2 \end{array}$$



Relations between universes

We can prove (in Agda) that the two definitions of finite types are related:

 $\begin{array}{ll} \text{fromFin} : & (n \, : \, \mathbb{N}) \rightarrow \text{Fin } n \rightarrow [\![\text{ natCode } n \,]\!] \\ \text{toFin} & : & (C \, : \, \text{Code}) \rightarrow [\![\, C \,]\!] \rightarrow \text{Fin } (\text{size } C) \\ \text{toFromId} : & \{n \, : \, \mathbb{N}\} \ (i \, : \, \text{Fin } n) \rightarrow \\ & i \equiv \text{toFin } (\text{natCode } n) \ (\text{fromFin } i) \end{array}$



Adding recursion

A universe for polynomial functors:

data Code : Set where

We interpret codes as type constructors now:



Mapping over functors

We traverse the structure, only modifying parameter positions:

```
\begin{array}{rll} \text{map} & : \; \{X \: Y \: : \: Set\} \to (C \: : \: Code) \to \\ & & (X \to Y) \to [\![ \: C \: ]\!] \: X \to [\![ \: C \: ]\!] \: Y \\ \text{map} \: c0 & f() \\ \text{map} \: c1 & f \: tt & = \: tt \\ \text{map} \: (C \oplus D) \: f(\mathsf{inj}_1 \: x) \: = \: \mathsf{inj}_1 \: (\mathsf{map} \: C \: f \: x) \\ \text{map} \: (C \oplus D) \: f(\mathsf{inj}_2 \: y) \: = \: \mathsf{inj}_2 \: (\mathsf{map} \: D \: f \: y) \\ \text{map} \: (C \otimes D) \: f(x, y) \: = \: \mathsf{map} \: C \: f \: x \: , \: \mathsf{map} \: D \: f \: y \\ \text{map} \: \mathsf{rec} & f \: x \: = \: f \: x \end{array}
```



Taking fixed points

We plug in the data structure itself for the parameter position:

data μ (C : Code) : Set where $\langle - \rangle$: $\llbracket C \rrbracket (\mu C) \rightarrow \mu C$



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```
data \mu (C : Code) : Set where
\langle - \rangle : \llbracket C \rrbracket (\mu C) \rightarrow \mu C
```

Example: Binary trees.

```
BinTree : Set
BinTree = \mu (c1 \oplus (rec \otimes rec))
leaf : BinTree
leaf = \langle inj_1 tt \rangle
true : BinTree \rightarrow BinTree \rightarrow BinTree
true I r = \langle inj_2 (I, r) \rangle
```



Generically traversing a recursive structure

cata : {C : Code} {X : Set} \rightarrow ([[C]] X \rightarrow X) \rightarrow μ C \rightarrow X cata {C} ϕ (x) = ϕ (map C (cata ϕ) x)

height : BinTree $\rightarrow \mathbb{N}$ height = cata [const 0, λ (x, y) \rightarrow 1 + max x y]



What's next?

Many approaches that have been tried in Haskell over the years are similar to the one we have just seen:

- regular library
- PolyP adds a parameter slot (so we can model lists, labelled trees, etc.)
- multirec library adds an index to the rec constructor, so that we can define fixed points of mutually recursive types



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Many approaches that have been tried in Haskell over the years are similar to the one we have just seen:

- regular library
- PolyP adds a parameter slot (so we can model lists, labelled trees, etc.)
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Agda helps us:

- to relate and understand all these approaches,
- to generalize even further,
- to prove properties of the resulting generic functions.



How many universes do we need?

Without dependent types (Haskell):

- Defining one universe is ok, but mapping between universes is infeasible.
- We have to decide which representation we want to use.
- But the choice is difficult.
- Simple universes represent less types but allow more functions to be defined.

With Agda, we do not have to decide:

- We can define functions generically over a "suitable" universe.
- We can change representations as needed.
- Ideally, we'd model the complete data construct as a universe (levitation).



Programming generically within Agda

Dependent types encourage us to make more distinctions than we are used to make:

- lists,
- vectors,
- sorted lists,
- lists with an even number of elements,
- lists containing only even numbers.

All of these become different **types**, yet we still want to perform similar **operations**.



We need more generic tools and special-purpose universes. Examples:

- Many list-like structures can be represented as reflexive transitive closures of suitable binary relations.
- We can relate unconstrained data structures such as lists to constrained data structures such as vectors by a generic process called algebraic ornamentation.



Conclusions

- Datatype-generic programming allows code to be reused more often.
- Generic functions are very abstract, but the types help you to write them.
- The stronger the type system, the more important (but also the easier) generic programming becomes.
- With dependent types, generic programming is just (ordinary) programming.
- Developing dependently typed generic programs is fun.

Thanks for listening – Questions?

